

WE LOOK AFTER THE EARTH BEAT

From ISS to Exploration

"Increasing Station Utilization Across All
Research Areas"
NanoRacks Workshop, Leiden (NL), Dec. 2015

THALES ALENIA SPACE INTERNAL

ThalesAlenia
A Thales / Finmeccanica Company Space

83230357-DOC-TAS-EN-002

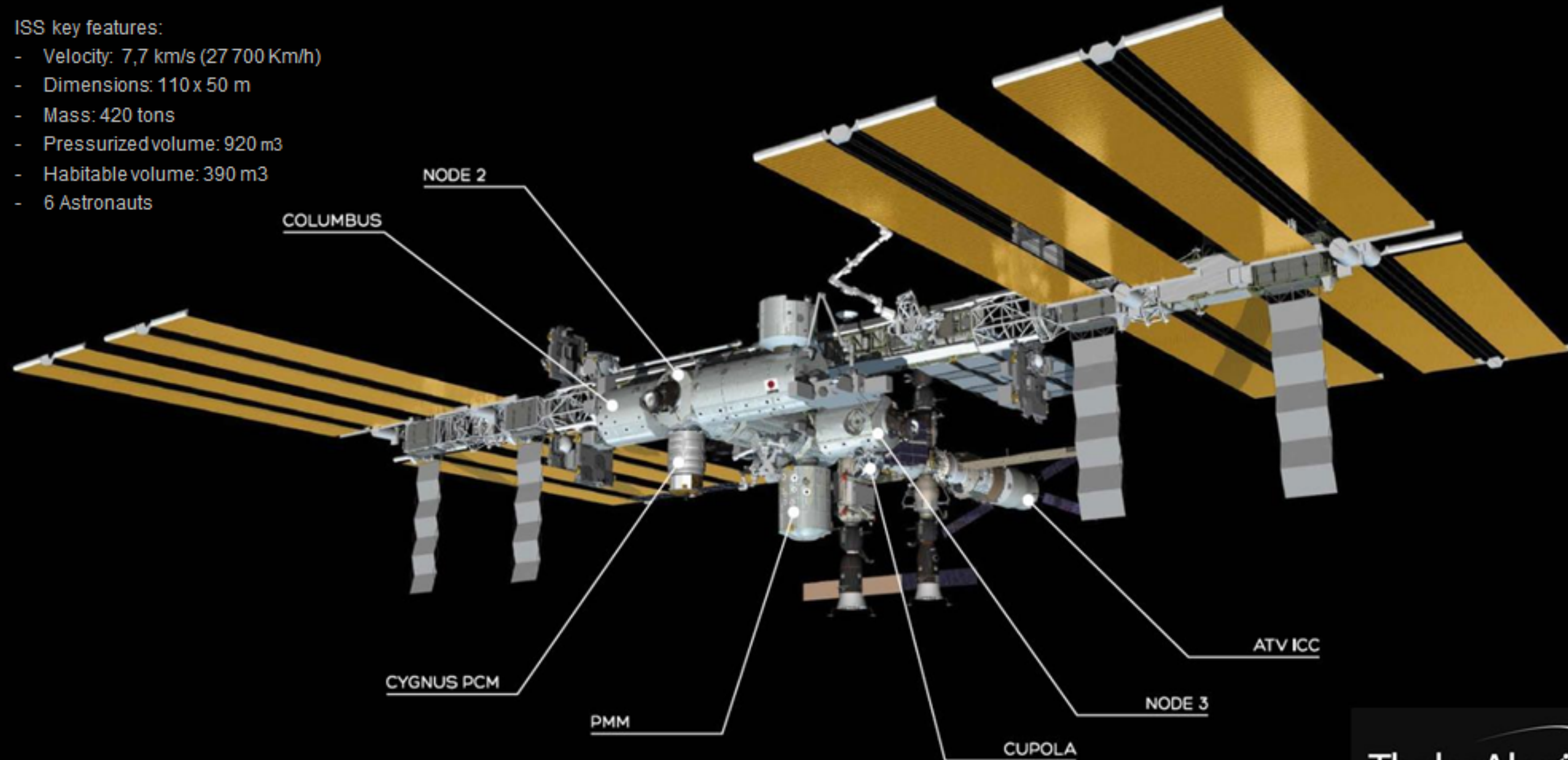
International Space Station (ISS): what done

2

INTERNATIONAL SPACE STATION elements built by Thales Alenia Space

ISS key features:

- Velocity: 7,7 km/s (27 700 Km/h)
- Dimensions: 110 x 50 m
- Mass: 420 tons
- Pressurized volume: 920 m³
- Habitable volume: 390 m³
- 6 Astronauts



ISS: in work, ESA EDR2

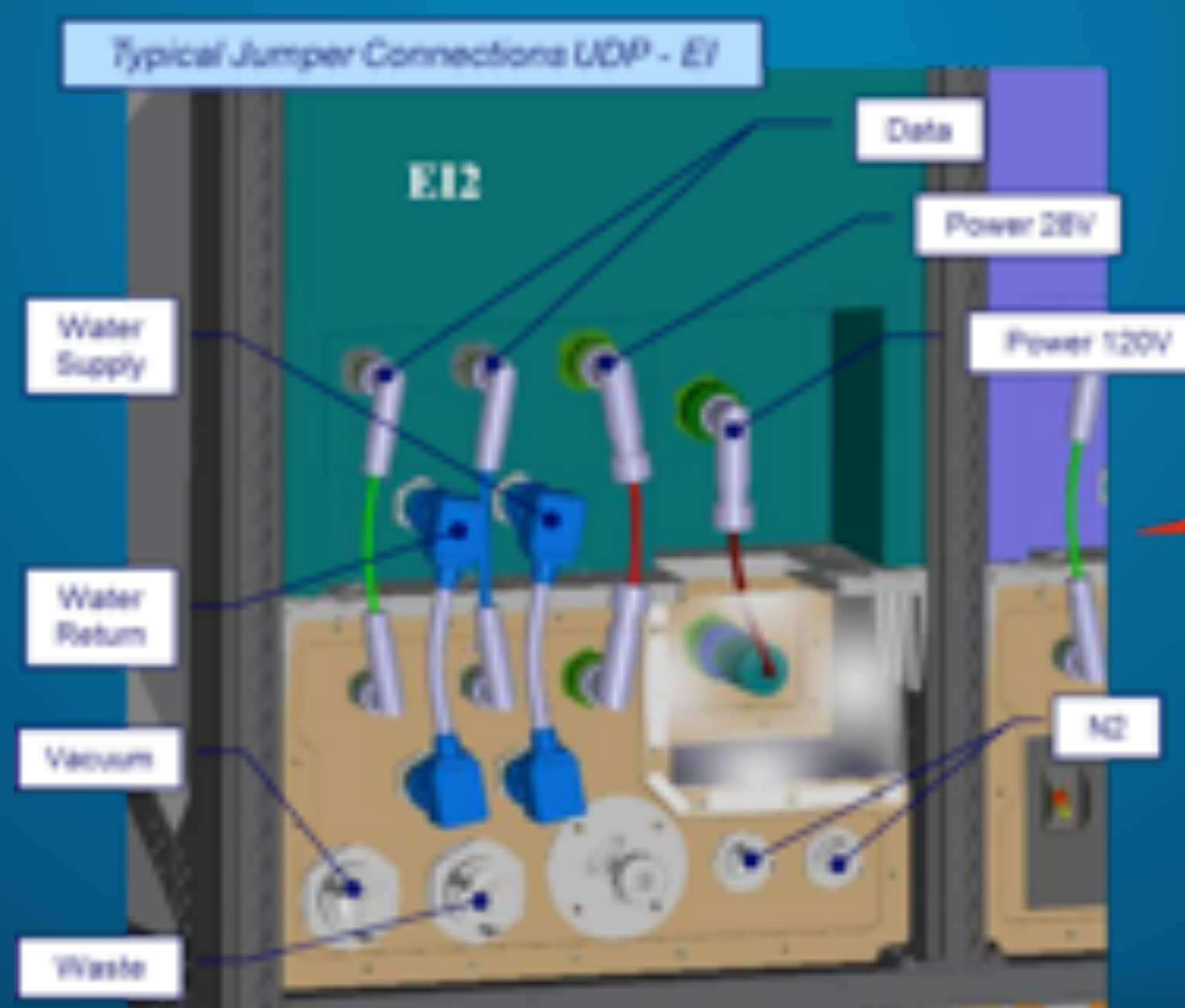
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A Payload System Facility to enable flexible accommodation of short turnaround payloads (Experiment Inserts), by providing the necessary mechanical / functional interfaces and resources

Available Resources for EIs

- Cooling Water
- Nitrogen
- Waste & Vacuum I/F
- Power (120V and 28V)
- Data Link

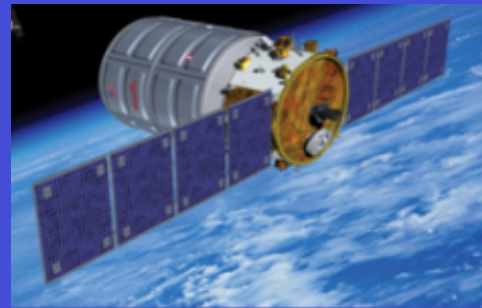
Planned for launch on HTV8 in Autumn 2018



Typical Configuration on orbit with EIs installed

TAS-I Exploration Roadmap

Commercial Transportation Services



Inflatable modules



Technology Demonstrators



Robotics



ISS Test Bed for Exploration



ISS

Orbiter Return Module (LPSR)



Orion ESM



Habitat



Beyond LEO (Cislunar)

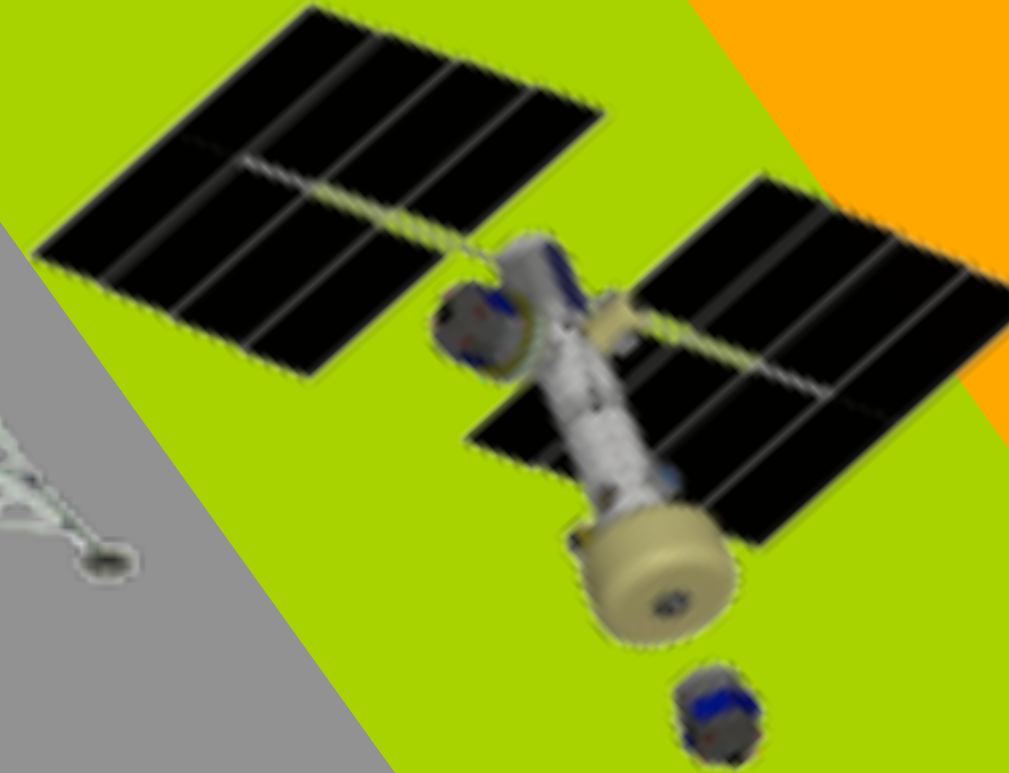
Lunar Lander & Ascent vehicle



Press. Rover

Moon

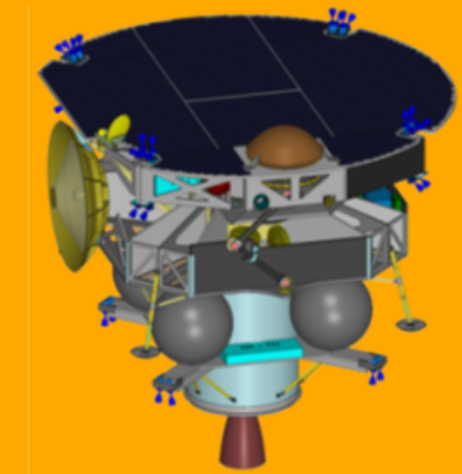
Long Duration (Deep Space) Habitat



Deep Space

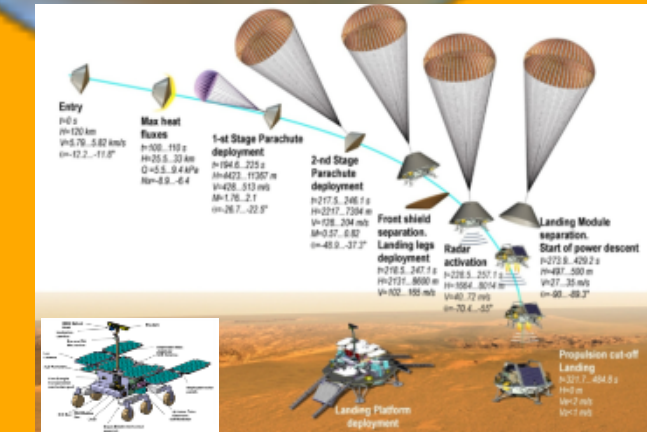


Mars



Post-EXM

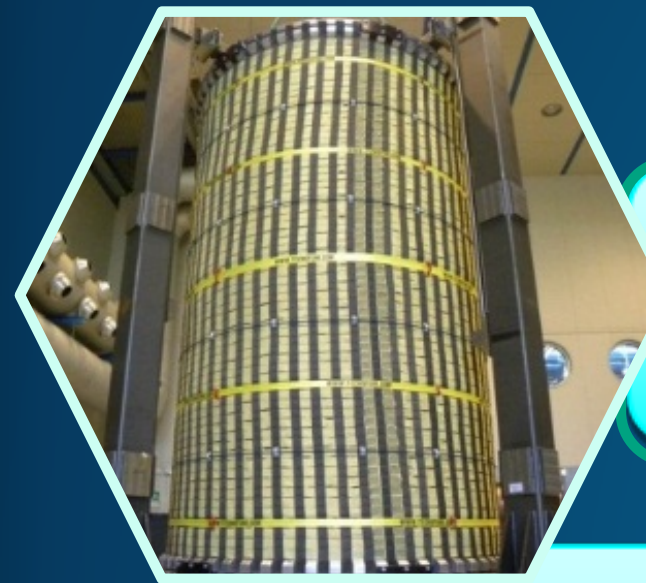
ExoMars



Incremental, multi-step approach thru enabling technologies development, robotic missions and outposts set-up to support human missions

TAS-I Technologies & Products for Exploration

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Environmental
Control

Advanced
Energy Storage

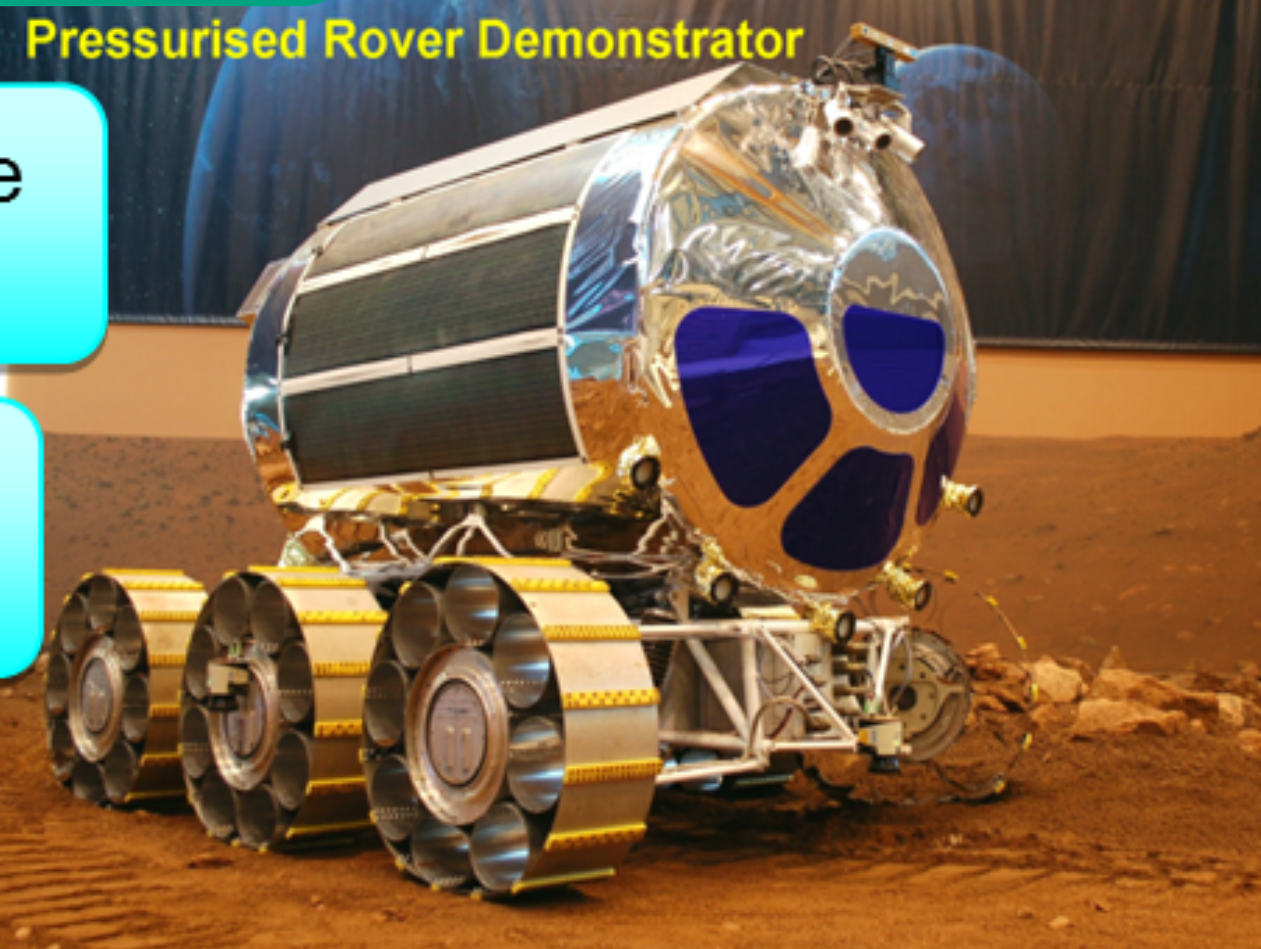
Ultra-light
Structures

Human-machine
Interface

Rigid & Inflatable
Structures

Pressurised
Structures

Pressurised Rover Demonstrator

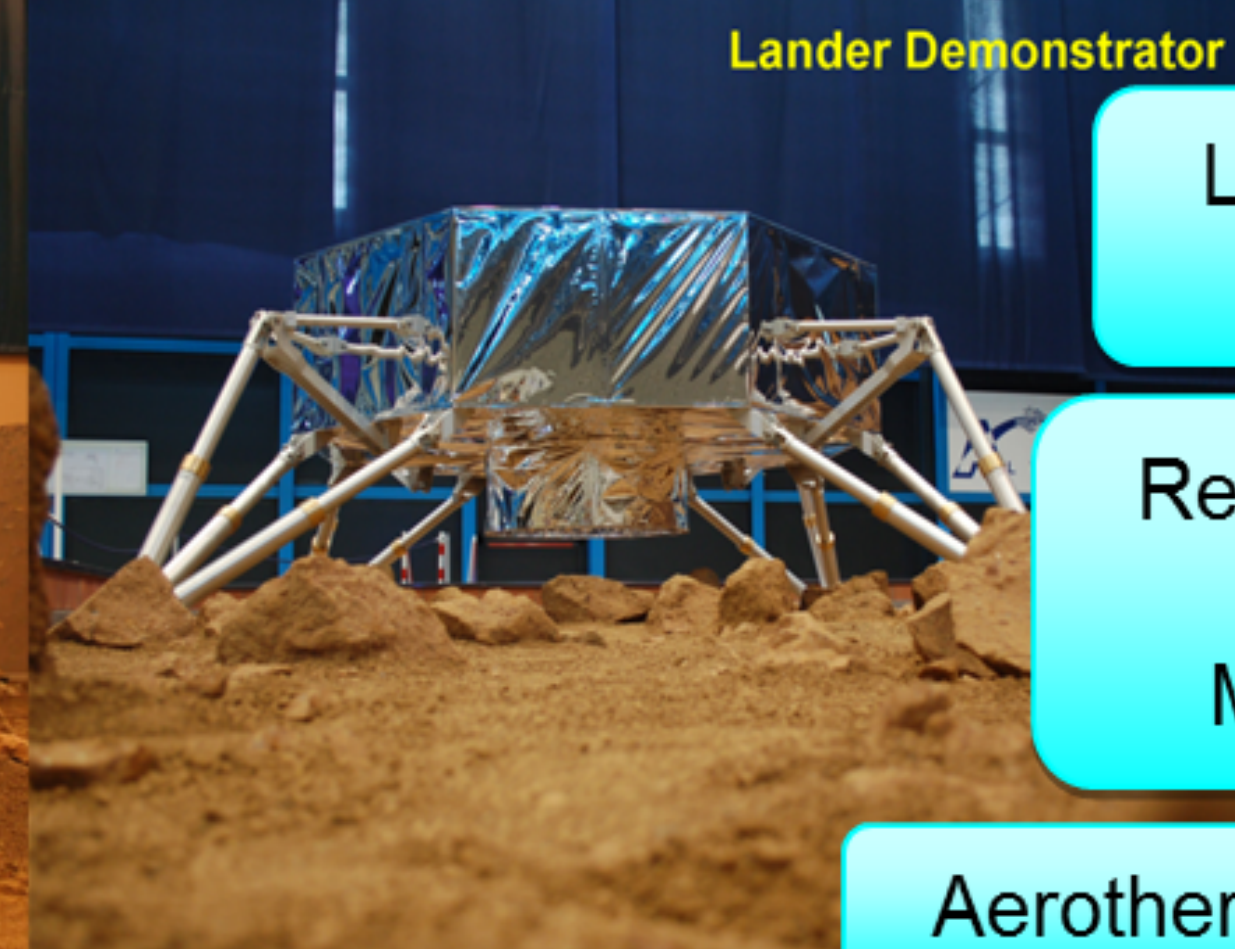


Locomotion &
Mechanisms

Navigation &
Guidance

Health Management
Systems

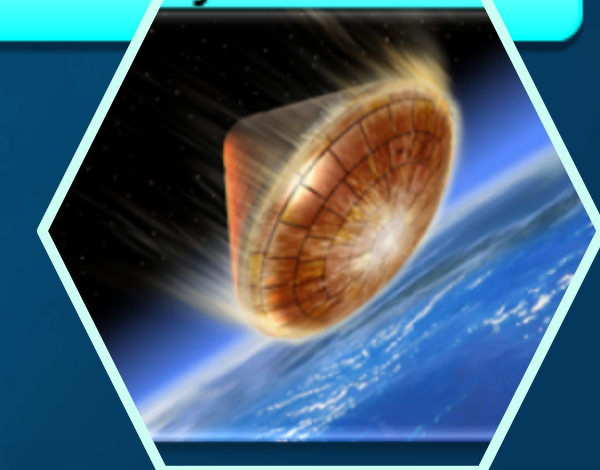
Lander Demonstrator



Landing/Ascent
System

Rendez Vous &
Docking
Mechanism

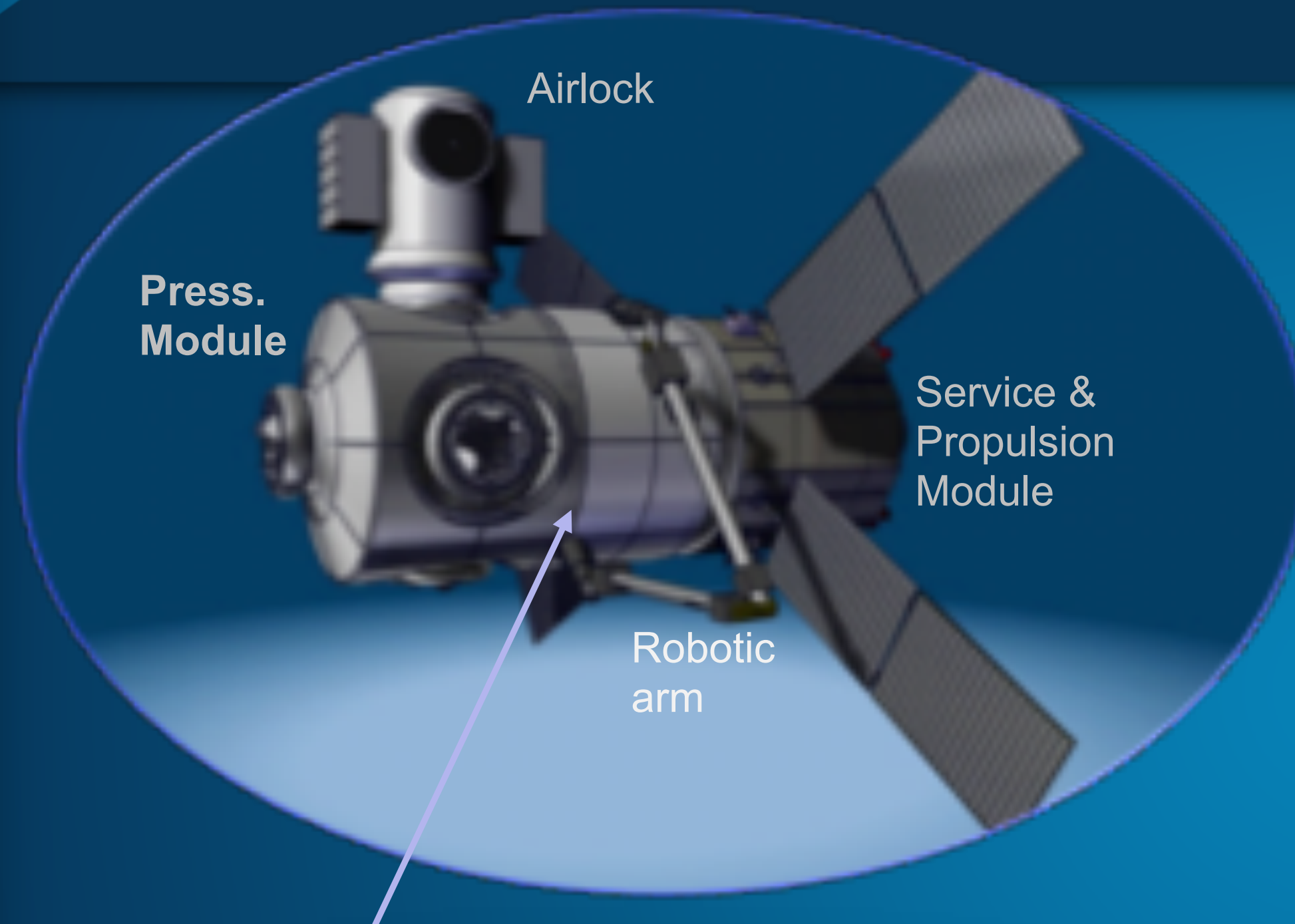
Aerothermodynamics



Cis-Lunar Habitat

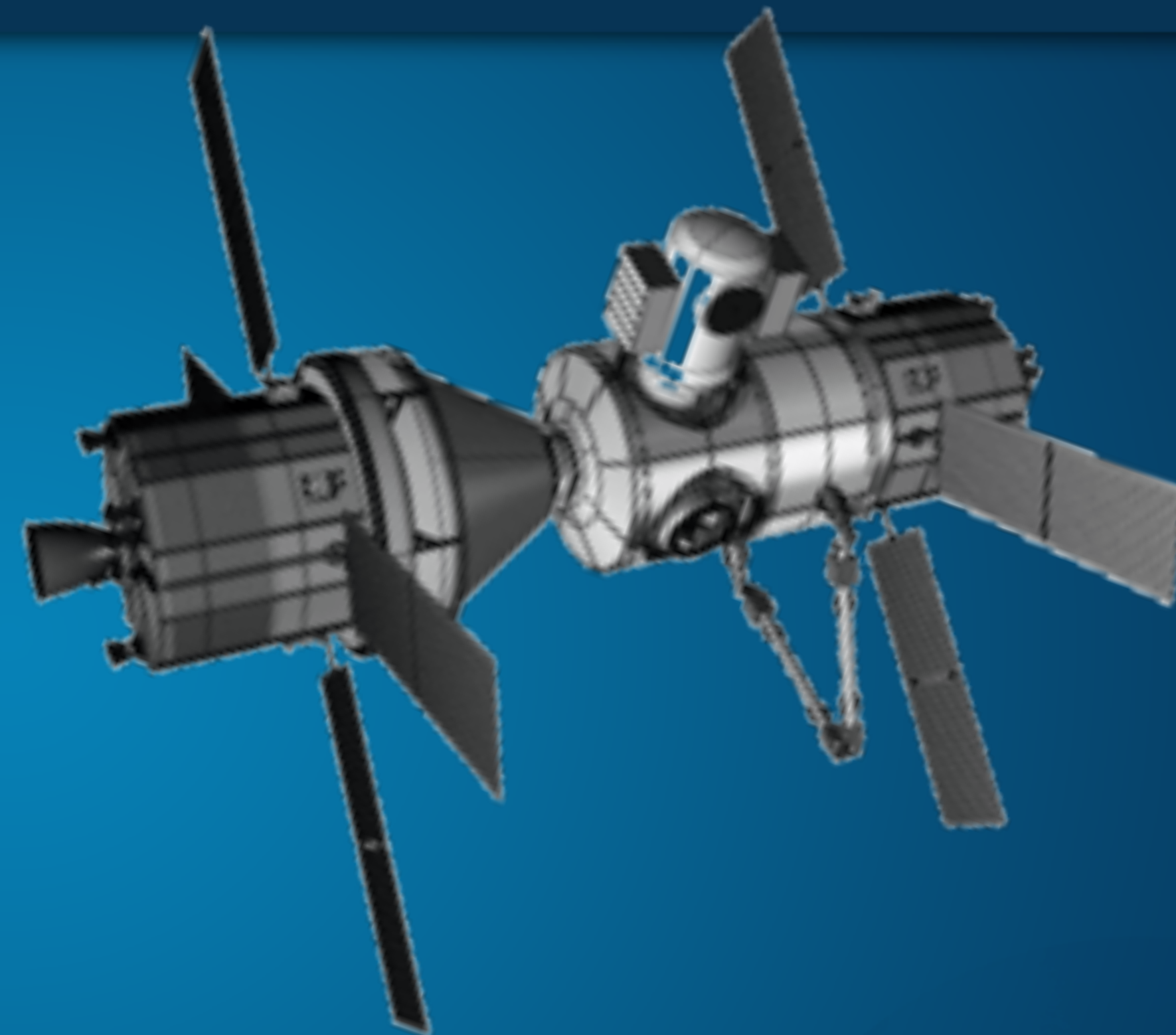
Operated on a crew-tended base for short visit (30-45 days). Relying on Orion system when docked to it. Periodically resupplied by Cargo Carriers.

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Node-like derived Habitation Modules

(dimensions and number of docking ports mission-dependent)



- Inspired by design heritage of ISS Pressurized Modules
- Simple yet robust by exploiting enhanced design features (lighter structures, MMOD protection integrated with thermal control,..)
- Evolvable, flexible, and modular, conceived as a platform to prove the technologies to take humans into deep space
- Supporting automation, tele-operations, robotics

ISS, IOV for Exploration: Robotic Tele-Operation

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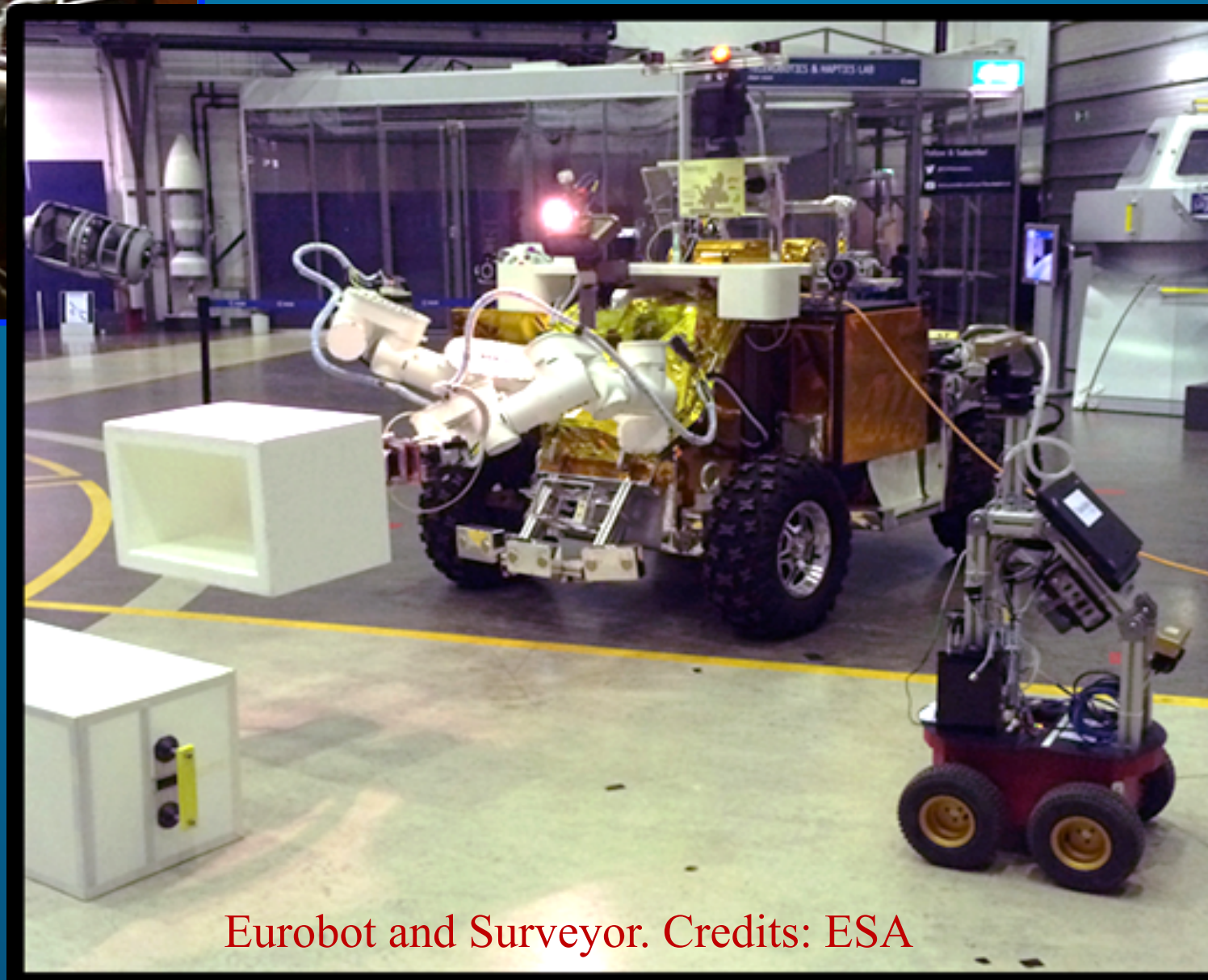


Astronaut Andreas Mogensen operates Robots in space using ELIOS. (Eurobot fLight cOntrol Station) MMI. Credits: Col-CC cam

The test from ISS mimics and aims to proving capability to tele-operate robots / rovers on planets surface from space orbiting outposts, a key feature for future exploration missions

ISS-based crew operation of multiple robots on Earth.

METERON “SUPVIS-E SDM (Short Duration Mission)” test successfully executed Sept. 2015 from ISS using TAS developed Flight MMI. Formal test planned early 2016.



Eurobot and Surveyor. Credits: ESA

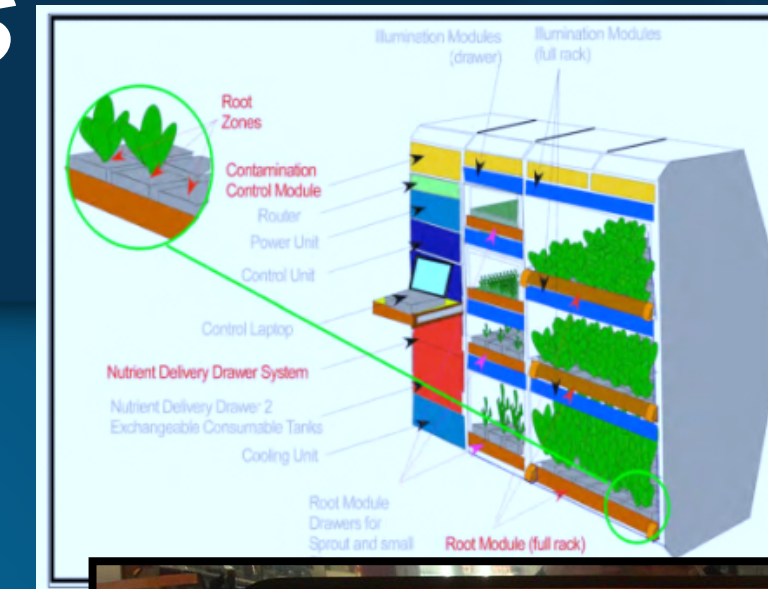
The scenario in place was the inspection and maintenance of an instrumented Lander Mock-up, and included proximity rover navigation, manipulation and computer vision technologies.

TAS EGP (ESA contract) and Surveyor Rover (STEPS2) at ESTEC premises during tele-operation from ISS

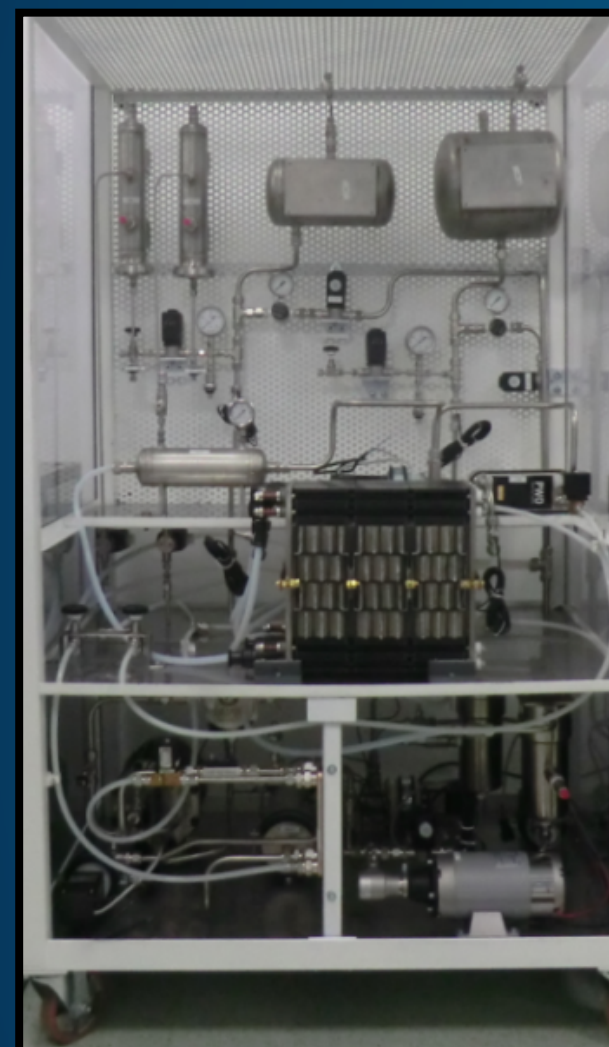


ISS, IOV for Exploration: Opportunities

Potential technologies for In-Orbit Validation @ ISS

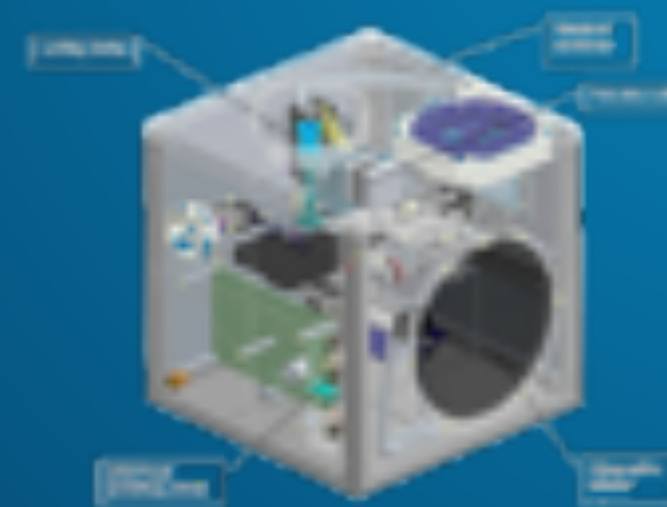


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Regenerative Fuel Cell System (RFCS)

Validation of high density energy storage systems (~400 Wh/kg) for future space exploration applications (e.g. rovers, planetary base), by demonstrating critical functions in micro-g (phase separation, fluid dynamics inside cells)



Wire Feed Metal Deposition 3D Printing

To assess in orbit the process building parameters, and on ground the returned sample performances (metallurgical properties, defects, residual stresses,...), to enable capabilities for future in flight maintenance and repair



Augmented (and Virtual) Reality techniques to facilitate on orbit operations